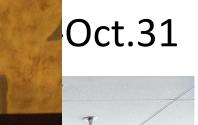
## CMA report

**Xueshun Shen** 

WGNE28, Toulouse, Nov.2012



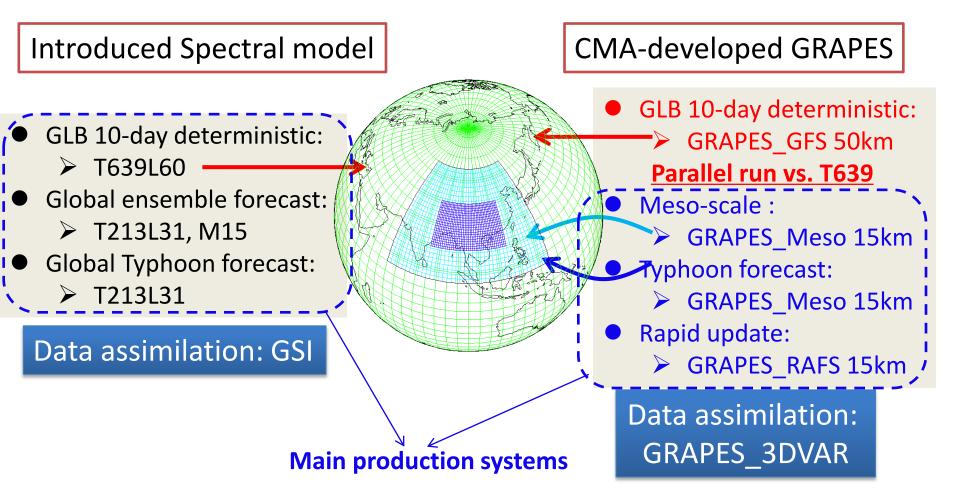


香山村

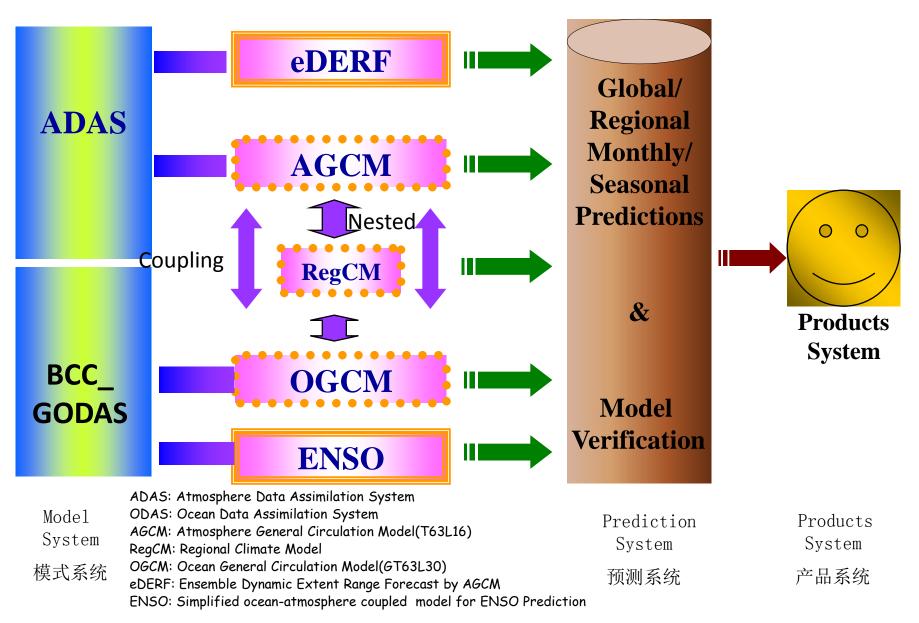
# Outline

- Production systems
  - Current status
  - Upgrade activities in 2012
  - Next 2-year plan
- Research Issues
  - New dynamics
- Chinese satellites and plan
- New computer plan

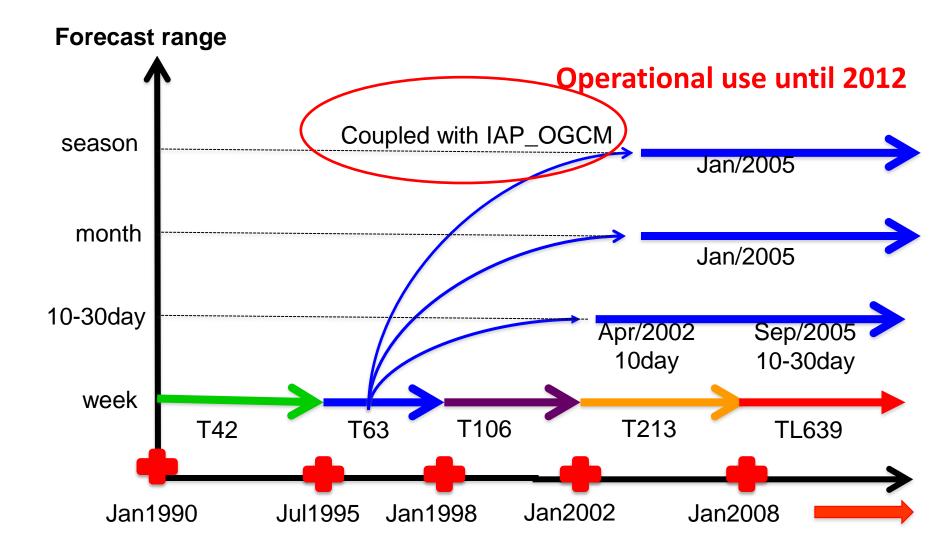
## **CMA Operational NWP System**



# Monthly, seasonal and annual prediction system (DCMPS1.0)



## History of CMA monthly/seasonal prediction system



## The satellite data used in T639L60 GSI

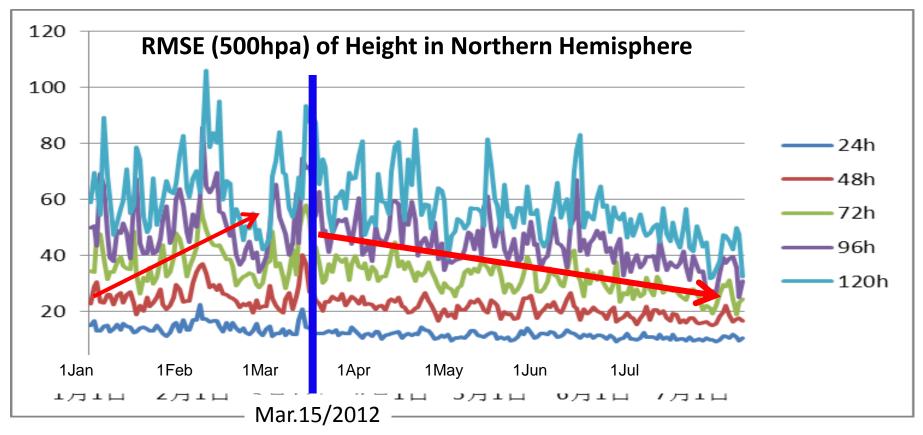
NOAA POES some channels:Operational with limitationsDegraded performanceNot operational

Need to add new satellite data into GSI to keep the model performance

http://www.oso.noaa.gov/poesstatus/ (

Active Spacecraft and Mission Status				
Spacecraft	Mission Operational Status			
<u>METOP-A</u>	AM Primary			
<u>NOAA 11</u>	Decomissioned 16 June 2004.			
<u>NOAA 12</u>	Decommissions 10 Aug 2007			
<u>NOAA 14</u>	Decommission on 23 May 07			
HOAA 15	AM Secondary			
<u>NOAA 16</u>	PM Secondary			
<u>NOAA 17</u>	AM Backup			
<u>NOAA 18</u>	PM Secondary			
<u>NOAA 19</u>	PM Primary			

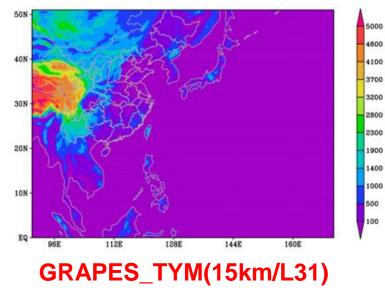
# Added NOAA-18 radiance, to stabilize the performance of operational spectral model system



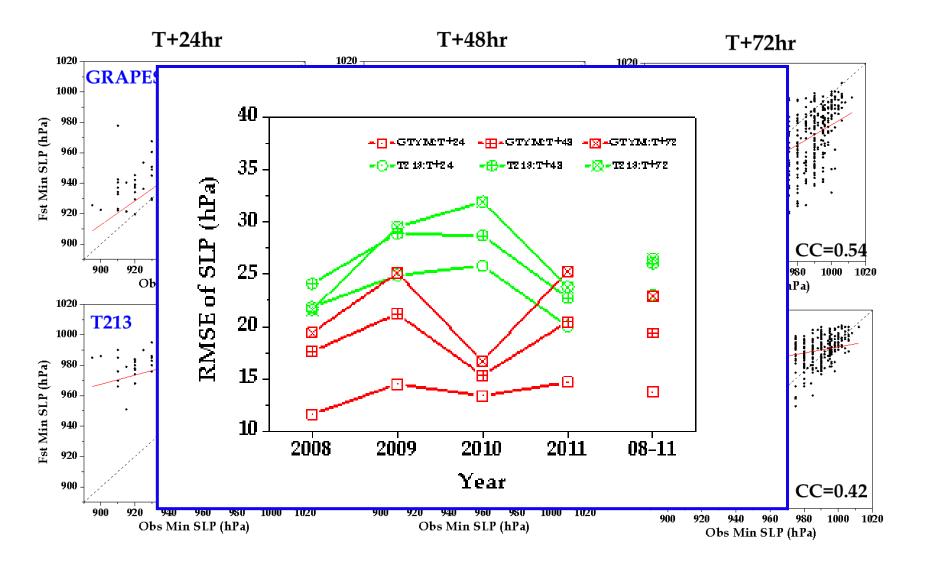
Before March 15 2012, the satellite data we used in NWP include the microwave radiances of NOAA-15/16/17. But the data quality of some instruments has declined, so NOAA-18 radiance data is added to T639.

# Newly implemented system GRAPES\_TYM

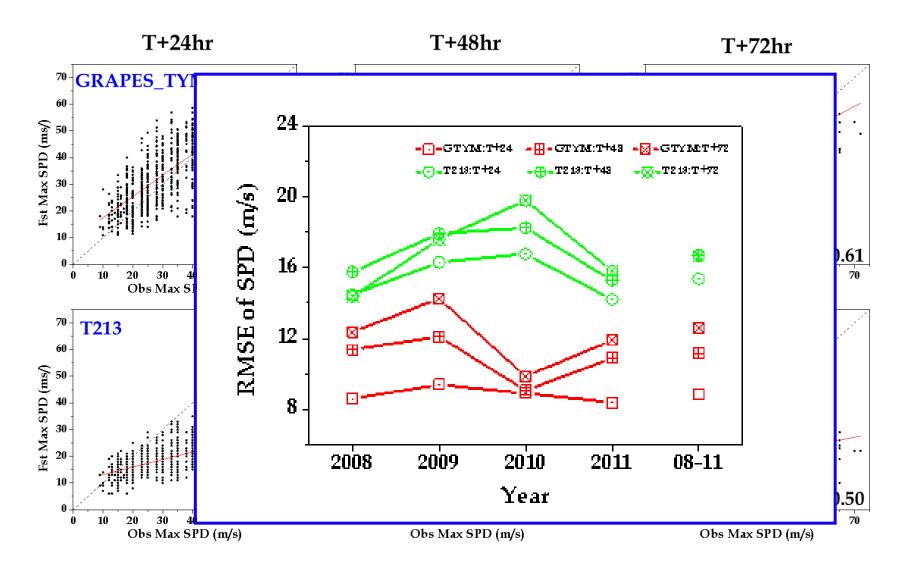
- For typhoon intensity forecast
- Based on GRAPES\_Meso
- 00UTC、12UTC: 72-hr forecast range
- Initial: vortex relocation & intensity adjustment



## MinSLP (Obs. Vs. FCST)



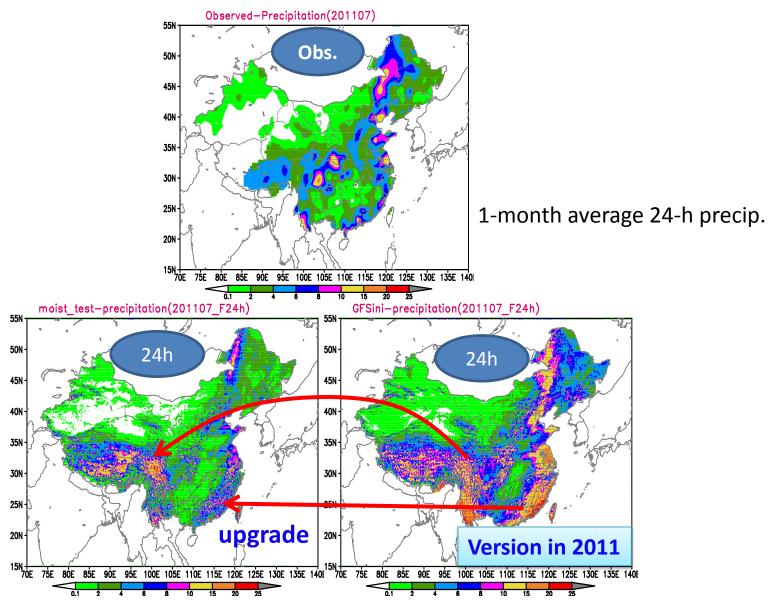
## Max SPD (Obs. vs. FCST)



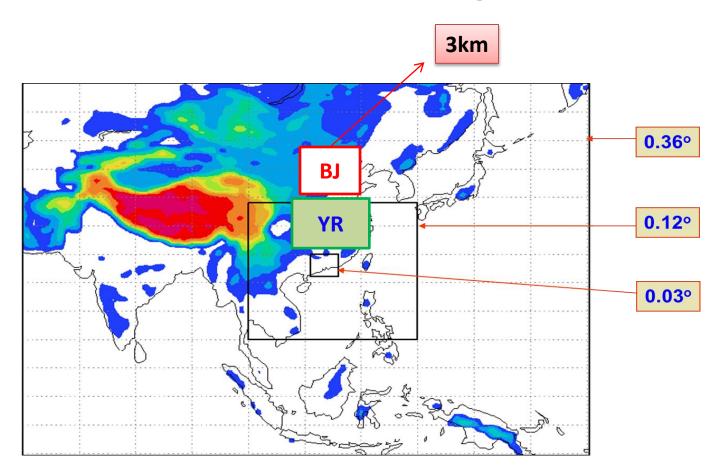
# GRAPES\_Meso upgrade

- Add 4<sup>th</sup>-order horizontal diffusion for stability
- Vertical coordinate from terrain-following Z to hybrid coordinate (Schar, 2002)
- Inclusion of thermal expansion effect in continuity equation
- Some bug fix in microphysics & land surface scheme
- Refinement of back ground error covariance in 3DVAR

#### Improve the precip. forecast

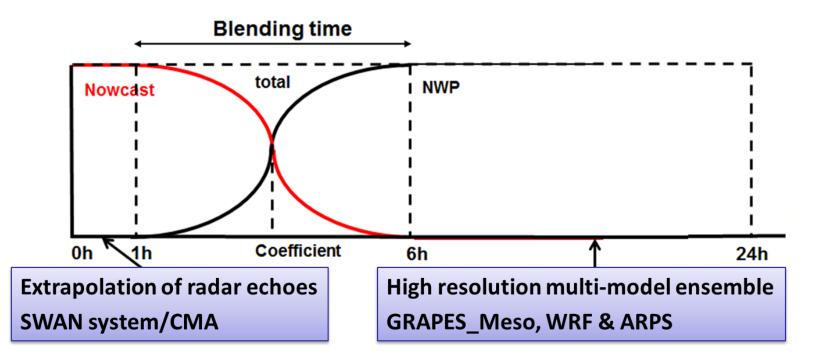


# Two high resolution windows testing

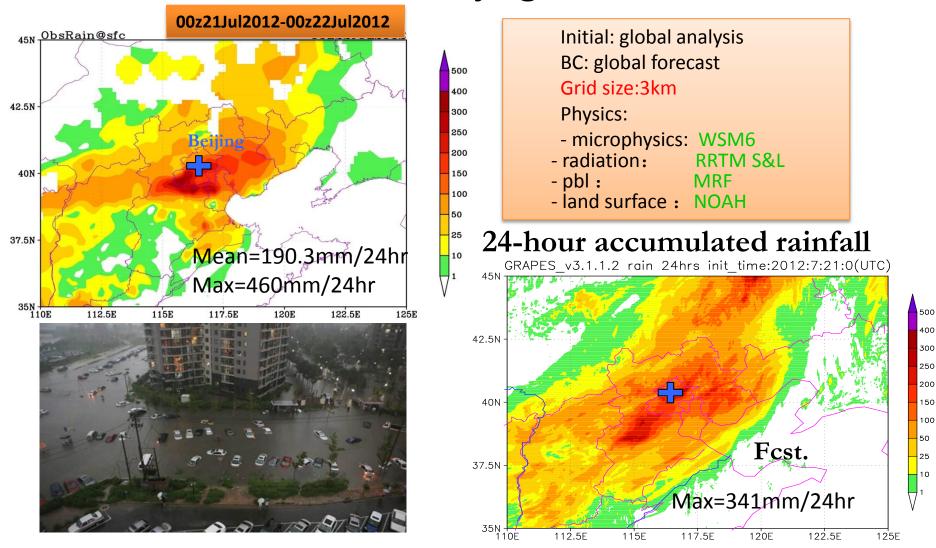


# Plan in next two years

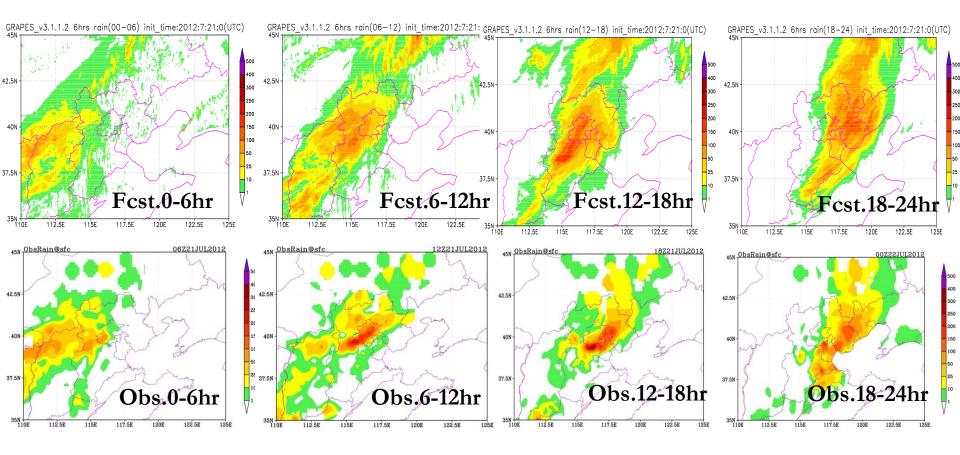
- Implement a very-short term forecast system with 3km resolution based on multi-model ensemble including GRAPES\_Meso, WRF and ARPS (collaborate with Nanjing University)
- Data assimilation: hybrid DA (3DVAR+EnKF) (collaborate with Ming Xue, Oklahoma Univ.)



## Heavy rainfall event on Jul.21/2012 Beijing



#### Comparison of precipitation every 6-hour between Obs. & Fcst.



# GRAPES\_GFS upgrade

## Model upgrade

# Conservative semi-Lagrangian scalar advection Revised simplified Arakawa-Schubert cumulus

- Maximum allowable cloud base mass flux defined based on local CFL (Jacob and Siebesma, 2003)
- Introduce the organized entrainment (Betchtold et al., 2008)
- Introduce convective momentum transport due to convection-induced pressure gradient force (Han & Pan, 2006)

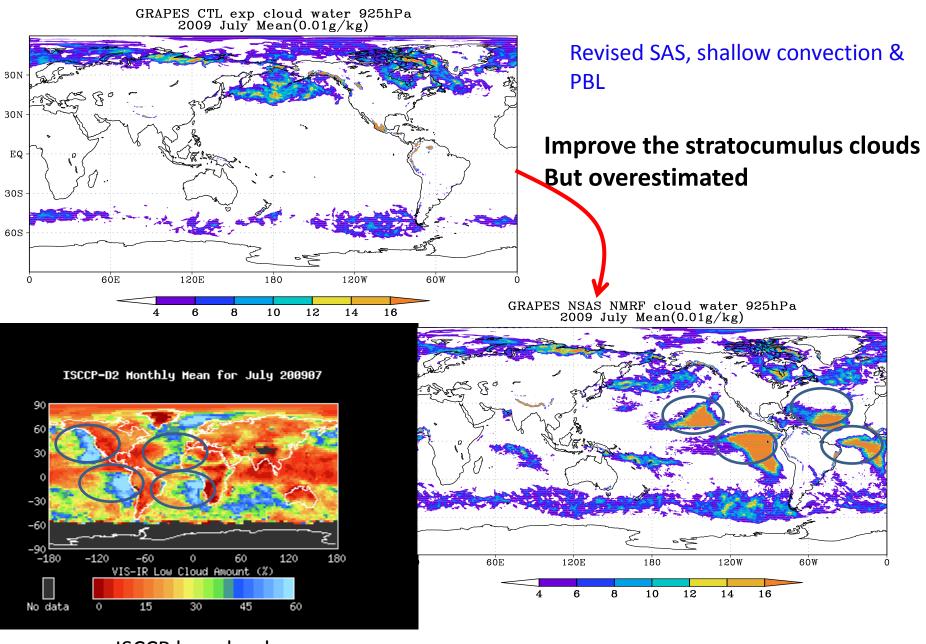
#### •Revised PBL

- Include stratocumulus-top driven turbulence mixing
- Use local diffusion for the nighttime stable PBL rather than a surface layer stability based diffusion profile

#### Revised shallow convection

- From turbulence diffusion based scheme to mass flux based
- Mass flux at cloud base is given as a function of the surface buoyancy flux (Grant, 2001)
- Entrainment rate based on Siebesma et al.2003

#### Microphysics + macro-scale cloud + prognostic cloud cover



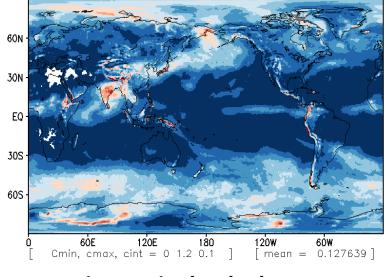
ISCCP low cloud cover July/2009

#### TCC - ISCCP

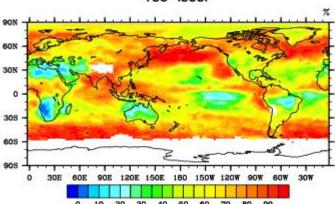
#### Microphysics + macro-scale cloud + prognostic cloud cover

#### Better Total Cloud Cover Over Indian monsoon region, Warm pool, East Asia & North Pacific





**Diagnostic cloud scheme** 



Total Cloud Fraction of Forecasted (TwoM\_Subgridc) for DAY.3 during 200907

0.8

0.7

0.6

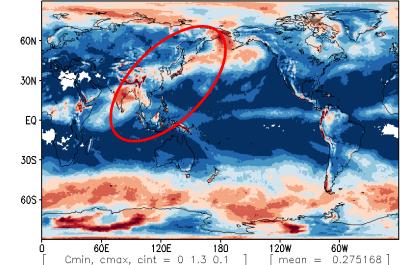
0.5

0.4

0.3

0.2

0.1



#### Prognostic cloud scheme

GrADS: COLA/IGES

GrADS: COLA/IGES

#### Monthly average, 3-day forecast

0.9

0.8

0.7

0.6

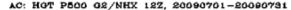
0.5

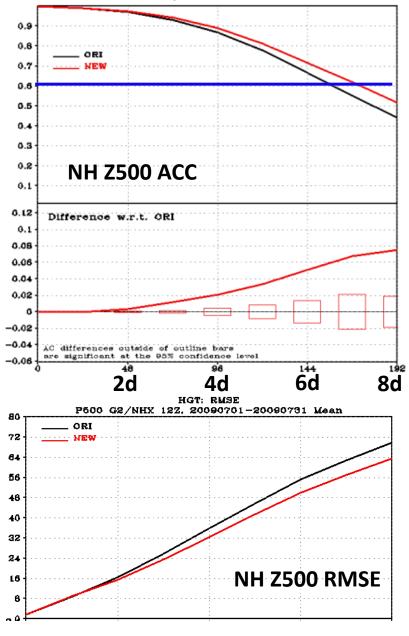
0.4

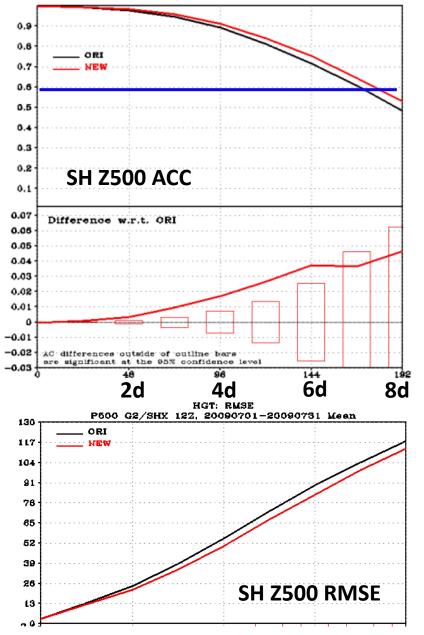
0.3

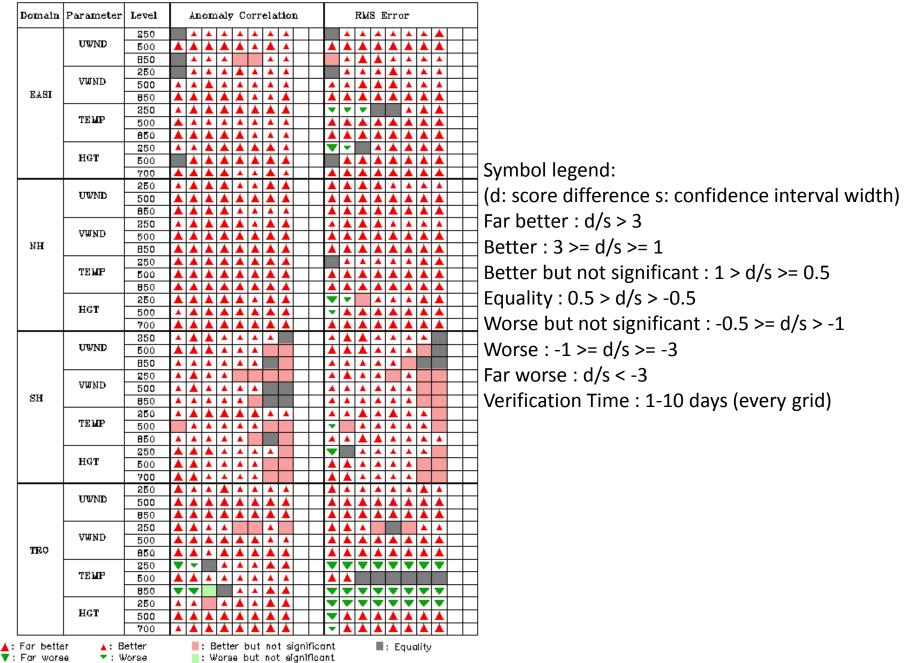
0.2

0.1









#### Score Card for new against ori

# GRAPES\_GFS upgrade

## **GRAPES 3DVAR upgrade**

- Arakawa-A & pressure level to model grid space analysis
- − RTTOV: RTTOV7 → RTTOV10
- Statistical method for balance relationship
- Add NOAA-19
- Revised bias correction of FY-3/MWTS
- Revised Height adjustment by 1DVAR for FY-2E AMV

## Satellite data in GRAPES

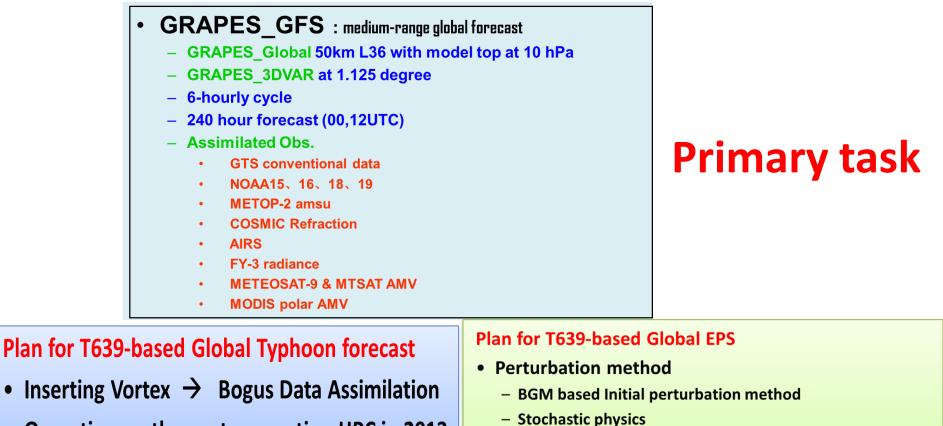
ATOVS microwave (NOAA 15 16) radiances ✓ NOAA-18 microwave radiance Metop microwave radiance ✓ GPS/RO refraction ✓ FY-3A /MWTS microwave radiance ✓ AIRS Hyper-spectral radiance ✓ FY-2E AMV wind ✓ NOAA-19 microwave radiance ✓ IASI Hyper-spectral radiance ✓ FY-3A /MWHS microwave radiance ✓ FY-3B /MWTS/MWHS microwave radiance

Data used

Will be used

Research

### Next 2-year operational implementation plan

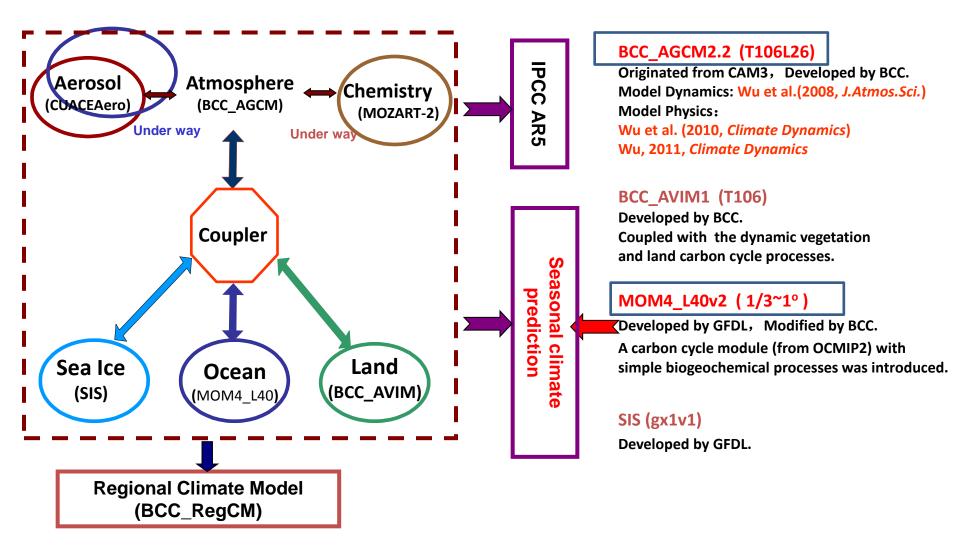


• Operation on the next generation HPC in 2013

#### • Operation on the next generation HPC in 2013

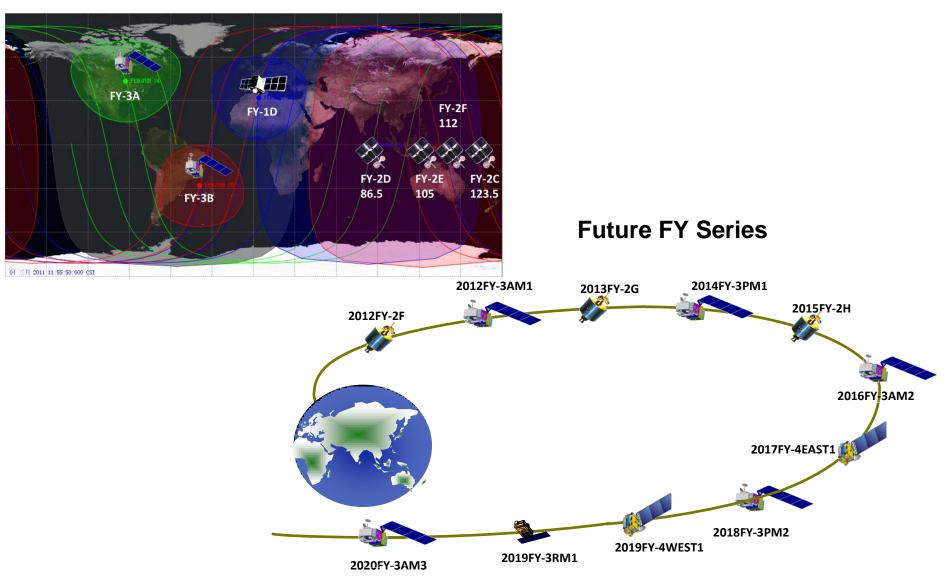
#### **2013:** new operational system for long-range prediction

Beijing Climate Center Climate System Model (BCC\_CSM)



## **Chinese Satellites**

On Orbit Satellite



#### **Tentative Schedule for Future FY Series**

Schedule	GEO.		LEO.	
Schedule	FY-2	FY-4	FY-3	
2011				
2012	Operational		<b>Operational (A.M. Orbit)</b>	
2013	Operational			
2014			<b>Operational (P.M. Orbit)</b>	
2015	Operational			
2016			<b>Operational (A.M. Orbit)</b>	
2017		<b>Operational (Optical SAT)</b>		
2018			<b>Operational (P.M. Orbit)</b>	
2019		Operational (Optical SAT)	<b>Operational (Rain Fall Massion)</b>	
2020			<b>Operational (A.M. Orbit)</b>	

### FY-3A/B follow-on

FY-3 OPERATIONAL SATELLITE INSTRUMENTS	FY-3C	FY-3D	FY-3E	FY-3F
MERSI – Medium Resolution Spectral Imager $(I, II)$	√(I)	√(II)	√(II)	√(II)
MWTS – Microwave Temperature Sounder (II)	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$
MWHS – Microwave Humidity Sounder (II)	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$
MWRI – Microwave Radiation Imager	$\checkmark$	$\checkmark$		$\checkmark$
WindRAD - Wind Radar			$\checkmark$	
GAS - Greenhouse Gases Absorption Spectromete		$\checkmark$		$\checkmark$
HIRAS – Hyperspectral Infrared Atmospheric Sounder		$\checkmark$	$\checkmark$	$\checkmark$
OMS – Ozone Mapping Spectrometer			$\checkmark$	
GNOS – GNSS Occultation Sounder	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$
ERM – Earth Radiation Measurement (I, II)	√(I)		√(II)	
SIM – Solar irritation Monitor (I, II)	√(I)		√(II)	
SES – Space Environment Suite	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$
IRAS – Infrared Atmospheric Sounder	$\checkmark$			
VIRR – visible and Infrared Radiometer	$\checkmark$			
SBUS – Solar Backscattered Ultraviolet Sounder				
TOU – Total Ozone Unit				

#### FY-3C/D/E/F Payload Configuration

FY-3 series is expected to last its measurements at least 15 years with additional four satellites. There are **16 improved or new instruments** will be configured from FY-3C to FY-3F in the schedule.

#### **New Instruments**

■ HIRAS (Hyperspectral Infrared Atmospheric Sounder) is an IASI/Metop-like instrument to improve the measured temperature and moisture profile instead of the IRAS

• OMS (Ozone Mapping Spectrometer) is a SCIAMACHY/Envisat-like instrument to detect the ozone and the other atmospheric chemical species as well instead of the suite of TOU and SBUS. The total column content and the profile of trace gases can be retrieved from the nadir view and limb view separatively.

WindRAD (Wind Radar) will measure the sea wind

**GAS** (Greenhouse Gases Absorption Spectrometer) will measure the CO2 and CH4 globally

**GNOS** (GNSS Occultation Sounder) will improve the measured temperature and moisture profile at the upper atmosphere

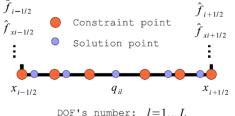
## **Research Activities**

## New dynamic core

#### Based on multi-moment constrained finite volume method

Multi-moment constrained finite volume method

Definition of multi-moments: the line-integrated average value (LIA moment), the point value (PV moment) and the derivative value (DV moment)



#### **Reconstruction:**

A Lagrange interpolation polynomial of tdegree (L-1) is constructed as

DOFs and multi-moment constraints are connected via the reconstruction polynomial

X. L. Li, C. G. Chen, X. S. Shen and F. Xiao, 2012: A multi-moment constrained finite volume model for non-hydrostatic atmospheric dynamics, Mon. Wea. Rev., in revision.

Li, X. L., X. S. Shen, X. D. Peng, F. Xiao, Z. R. Zhuang, and C. G. Chen, 2012: Fourth order transport model on yin-yang grid by multi-moment constrained finite volume scheme, Procedia Computer Science, 9, 1004-1013. Governing equations with the effects of topography in the curviliear Cartesian system

Reference state:

$$\rho(\mathbf{x}, t) = \bar{\rho}(z) + \rho'(\mathbf{x}, t)$$

local hydrostatic balance

$$p(\mathbf{x},t) = \bar{p}(z) + p'(\mathbf{x},t)$$
  $\frac{\partial \bar{p}}{\partial z} = -\bar{\rho}g$ 

$$(\rho\theta)(\mathbf{x},t) = \overline{(\rho\theta)}(z) + (\rho\theta)'(\mathbf{x},t)$$

Height-based terrain following coordinate

$$z(\zeta) = \zeta + z_s(x) \frac{\sinh[(z_T - \zeta)/s]}{\sinh(z_T/s)}$$

#### **Governing equations**:

$$\begin{split} \frac{\partial \rho'}{\partial t} + \frac{1}{\sqrt{G}} \left[ \frac{\partial (\sqrt{G}\rho u)}{\partial x} + \frac{\partial (\sqrt{G}\rho \tilde{w})}{\partial \zeta} \right] &= 0, \\ \frac{\partial (\rho u)}{\partial t} + \frac{1}{\sqrt{G}} \left[ \frac{\partial (\sqrt{G}\rho u^2 + \sqrt{G}p')}{\partial x} + \frac{\partial (\sqrt{G}\rho u \tilde{w} + \sqrt{G}G^{13}p')}{\partial \zeta} \right] &= 0, \\ \frac{\partial (\rho w)}{\partial t} + \frac{1}{\sqrt{G}} \left[ \frac{\partial (\sqrt{G}\rho w u)}{\partial x} + \frac{\partial (\sqrt{G}\rho w \tilde{w} + p')}{\partial \zeta} \right] &= -\rho' g, \\ \frac{\partial (\rho \theta)'}{\partial t} + \frac{1}{\sqrt{G}} \left[ \frac{\partial (\sqrt{G}\rho \theta u)}{\partial x} + \frac{\partial (\sqrt{G}\rho \theta \tilde{w})}{\partial \zeta} \right] &= 0, \end{split}$$

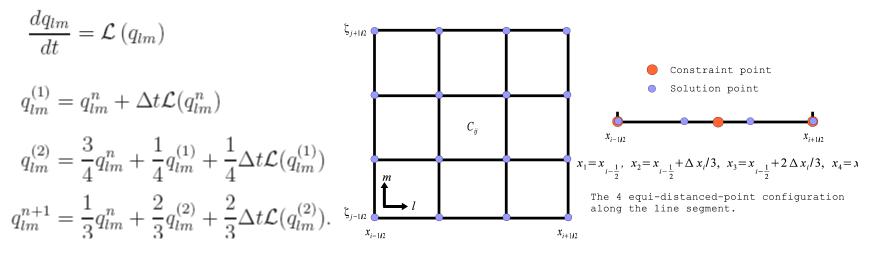
where the metric term  $\sqrt{G} = \frac{\partial z}{\partial \zeta}$   $G^{13} = \frac{\partial \zeta}{\partial x}$   $\tilde{w} = \frac{d\zeta}{dt}$ 

#### Spatial discretization: multi-moment constrained finite volume method

$$\frac{d}{dt}(q_{lm}) = \sum_{\beta=1}^{5} \mathcal{M}_{4l\beta}^{(x)} \mathcal{F}_{4\beta m} + \sum_{\beta=1}^{5} \mathcal{M}_{4m\beta}^{(\zeta)} \mathcal{G}_{4l\beta} + \mathcal{S}(q_{lm}), \text{ for } l, m = 1, 2, 3, 4.$$

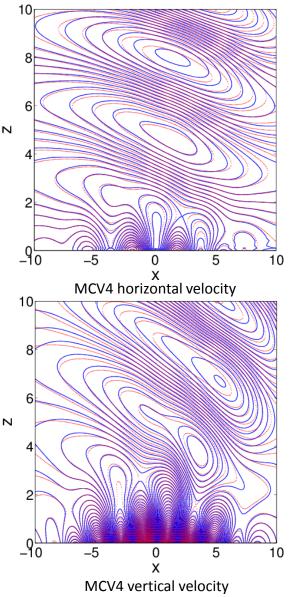
$$\mathbf{M}_{4}^{(x)} = \begin{bmatrix} 0 & 0 & -1 & 0 & 0 \\ \frac{4}{3\Delta x_{i}} & -\frac{4}{3\Delta x_{i}} & \frac{4}{27} & \frac{5}{27} & \frac{4\Delta x_{i}}{27} \\ \frac{4}{3\Delta x_{i}} & -\frac{4}{3\Delta x_{i}} & \frac{4}{27} & \frac{5}{27} & -\frac{4\Delta x_{i}}{27} \\ 0 & 0 & 0 & -1 & 0 \end{bmatrix} \text{ and } \mathbf{F}_{4}^{(x)} = \begin{bmatrix} \hat{f}_{1m} \\ \hat{f}_{4m} \\ (\partial_{x}\hat{f})_{1m} \\ (\partial_{x}\hat{f})_{4m} \\ (\partial_{x}\hat{f})_{6m} \end{bmatrix}} \mathbf{M}_{4}^{(\zeta)} = \begin{bmatrix} 0 & 0 & -1 & 0 & 0 \\ \frac{4}{3\Delta \zeta_{j}} & -\frac{4}{3\Delta \zeta_{j}} & \frac{4}{27} & \frac{5}{27} & \frac{4\Delta \zeta_{j}}{27} \\ \frac{4}{3\Delta \zeta_{j}} & -\frac{4}{3\Delta \zeta_{j}} & \frac{4}{27} & \frac{5}{27} & -\frac{4\Delta \zeta_{j}}{27} \\ 0 & 0 & 0 & -1 & 0 \end{bmatrix}} \text{ and } \mathbf{G}_{4}^{(\zeta)} = \begin{bmatrix} \hat{g}_{l1} \\ \hat{g}_{l4} \\ (\partial_{\zeta}\hat{g})_{l1} \\ (\partial_{\zeta}\hat{g})_{l4} \\ (\partial_{\zeta}\hat{g})_{6m} \end{bmatrix}}$$

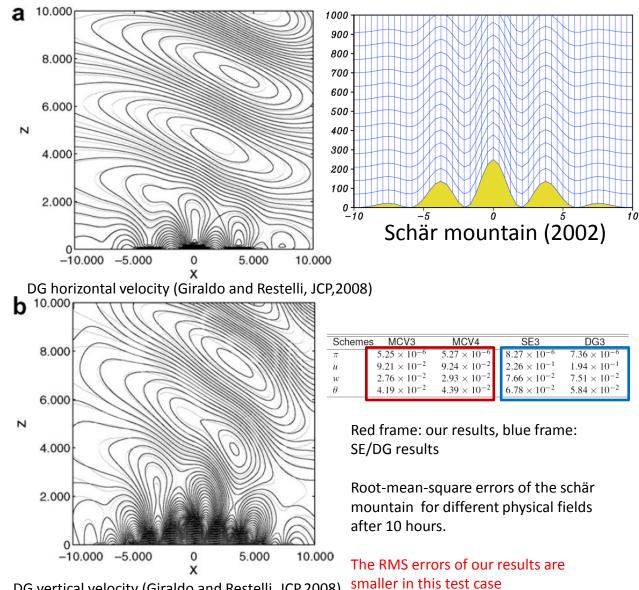
#### Time stepping: 3<sup>rd</sup> TVD Runge-Kutta method



The equidistant solution points within one single cell

#### **Red lines: analytic solution, blue lines: our results**

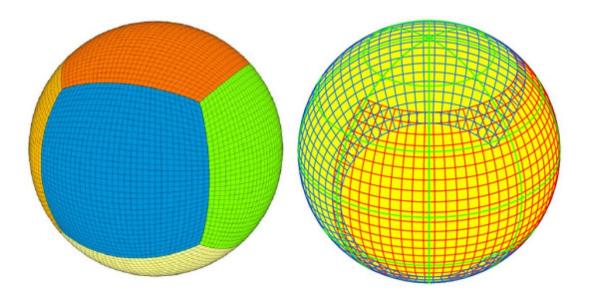




DG vertical velocity (Giraldo and Restelli, JCP,2008)

Near future plan

MCV (3<sup>rd</sup> and 4<sup>th</sup> order) + cubed grid or Yin-Yang grid



Further researches will be continued to develop 3D dynamical cores using the same methodology based on the popular structured spherical grids, such as structured cubed grid, Yin-Yang grid.

#### CMA's super computer system will be upgraded in 2013

	Oct. 2004- Now	Sep. 2009 – Now	2013-
	IBM Cluster1600	Sunway4000A	
Total Peak Performance	21.5 TFlops	33.75 TFlops	Will up to over 1000TFlops totally
Node Configuration	322×p655 nodes (8CPU/16GMEM) +58×p655 nodes (8CPU/32GMEM) +4×p690 nodes (32CPU/256GMEM)	168 Computing nodes (8CPU/36G MEM) +128 Computing nodes (12CPU/36G MEM) +16 IO nodes (24G MEM) +6 Server nodes (8CPU/24G MEM)	About 50000 cores 4GB memory/core
Network	IBM High Performance Switch 2*2GB/s (node to node)	Infiniband 80GB/s ( one-way Bidirectional bandwidth)	About 80GB/s( one-way Bidirectional bandwidth)
Storage	128TB	384TB	Will up to over <b>3000TB</b> totally

# **THANK YOU**